

## Forklift Starter and Alternator

Forklift Starters and Alternators - Today's starter motor is typically a permanent-magnet composition or a series-parallel wound direct current electrical motor together with a starter solenoid mounted on it. Once current from the starting battery is applied to the solenoid, mainly through a key-operated switch, the solenoid engages a lever which pushes out the drive pinion that is located on the driveshaft and meshes the pinion utilizing the starter ring gear that is found on the engine flywheel.

The solenoid closes the high-current contacts for the starter motor, which begins to turn. Once the engine starts, the key operated switch is opened and a spring in the solenoid assembly pulls the pinion gear away from the ring gear. This action causes the starter motor to stop. The starter's pinion is clutched to its driveshaft by an overrunning clutch. This permits the pinion to transmit drive in just a single direction. Drive is transmitted in this particular way through the pinion to the flywheel ring gear. The pinion continuous to be engaged, for instance as the operator did not release the key when the engine starts or if there is a short and the solenoid remains engaged. This causes the pinion to spin independently of its driveshaft.

The actions mentioned above would prevent the engine from driving the starter. This vital step stops the starter from spinning so fast that it could fly apart. Unless modifications were made, the sprag clutch arrangement would preclude the use of the starter as a generator if it was employed in the hybrid scheme discussed earlier. Usually a regular starter motor is intended for intermittent utilization that would stop it being utilized as a generator.

The electrical parts are made to be able to operate for approximately 30 seconds to be able to prevent overheating. Overheating is caused by a slow dissipation of heat is because of ohmic losses. The electrical parts are intended to save weight and cost. This is actually the reason most owner's instruction manuals intended for vehicles recommend the operator to stop for a minimum of ten seconds after each and every ten or fifteen seconds of cranking the engine, if trying to start an engine that does not turn over at once.

The overrunning-clutch pinion was introduced onto the market during the early 1960's. Previous to the 1960's, a Bendix drive was used. This particular drive system works on a helically cut driveshaft which consists of a starter drive pinion placed on it. As soon as the starter motor starts turning, the inertia of the drive pinion assembly allows it to ride forward on the helix, hence engaging with the ring gear. As soon as the engine starts, the backdrive caused from the ring gear allows the pinion to go beyond the rotating speed of the starter. At this moment, the drive pinion is forced back down the helical shaft and therefore out of mesh with the ring gear.

In the 1930s, an intermediate development between the Bendix drive was developed. The overrunning-clutch design which was made and launched in the 1960s was the Bendix Folo-Thru drive. The Folo-Thru drive consists of a latching mechanism along with a set of flyweights within the body of the drive unit. This was much better since the standard Bendix drive utilized to disengage from the ring as soon as the engine fired, although it did not stay functioning.

The drive unit is forced forward by inertia on the helical shaft as soon as the starter motor is engaged and begins turning. Next the starter motor becomes latched into the engaged position. Once the drive unit is spun at a speed higher than what is achieved by the starter motor itself, for example it is backdriven by the running engine, and after that the flyweights pull outward in a radial manner. This releases the latch and enables the overdriven drive unit to become spun out of engagement, thus unwanted starter disengagement could be avoided before a successful engine start.